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Certifying floating-point implementations using Gappa

Florent de Dinechin, Christoph Lauter, and Guillaume Melquiond

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Abstract

High confidence in floating-point programs requires proving numerical properties of final and intermediate values. One may need to guarantee that a value stays within some range, or that the error relative to some ideal value is well bounded. Such work may require several lines of proof for each line of code, and will usually be broken by the smallest change to the code (e.g. for maintenance or optimization purpose). Certifying these programs by hand is therefore very tedious and error-prone. This article discusses the use of the Gappa proof assistant in this context. Gappa has two main advantages over previous approaches: its input format is very close to the actual C code to validate, and it automates error evaluation and propagation using interval arithmetic. Besides, it can be used to incrementally prove complex mathematical properties pertaining to the C code. Yet it does not require any specific knowledge about automatic theorem proving, and thus is accessible to a wide community. Moreover, Gappa may generate a formal proof of the results that can be checked independently by a lower-level proof assistant like Coq, hence providing an even higher confidence in the certification of the numerical code. The article demonstrates the use of this tool on a real-size example, an elementary function with correctly-rounded output.

1 Introduction

Floating-point (FP) arithmetic was designed to help developing software handling real numbers. However, FP numbers are only an approximation to the real numbers. A novice programmer may incorrectly assume that FP numbers possess all the basic properties of the real numbers, for instance associativity of the addition, and waste time fighting the associated subtle bugs. Having been bitten once, he may forever stay wary of FP computing as something that cannot be trusted. As many safety-critical systems rely on floating-point arithmetic, the question of the confidence that one can have in such systems is of paramount importance, all the more as floating-point hardware, long available in mainstream processors, is now also increasingly designed into embedded systems.

This question was addressed in 1985 by the IEEE-754 standard for floating-point arithmetic [1]. This standard defines common floating-point formats (single and double precision), but it also precisely specifies the behavior of the basic operators $+,-,\times,\div$, and $\sqrt{}$. In the rounding mode to the nearest, these operators shall return the correctly rounded result, uniquely defined as the floating-point number closest to the exact mathematical value (in case of a tie, the number returned is the one with the even mantissa). The standard also defines three directed rounding modes (towards $+\infty$, towards $-\infty$, and towards 0) with similar correct rounding requirements on the operators.

The adoption and widespread use of this standard have increased the numerical quality and portability of floating-point code. It has improved confidence in such code and allowed construction of proofs of numerical behavior [2]. Directed rounding modes are also the key to enable efficient interval arithmetic [3], a general technique to obtain validated numerical results.

This article is related to the IEEE-754 standard in two ways. Firstly, it discusses the issue of proving properties of numerical code, building upon the properties specified by this standard. Secondly, one of our case studies will be the proof of the implementation of an elementary function (the logarithm) returning correctly-rounded results. Such correctly-rounded implementations will contribute to a better floating-point standard, where the numerical quality of elementary functions matches that of the basic operators.

Elementary functions were left out of the IEEE-754 standard in 1985 in part because the correct rounding property is much more difficult to guarantee than for the basic arithmetic operators. The problem will be exposed in detail in the sequel. In short, the correctness of the implementation of a correctly rounded function requires the a priori knowledge
of a bound on the overall error of evaluating $f(x)$. Moreover, this bound should be tight, as a loose bound negatively impacts performance [4, 5].

This article describes an approach to machine-checkable proofs of such tight bounds, which is both interactive and easy to manage, yet much safer than a hand-written proof. It applies to error bounds as well as range bounds. Our approach is not restricted to the validation of elementary functions. It currently applies to any straight-line floating-point program of reasonable size (up to several hundreds of operations).

The novelty here is the use of a tool that transforms a high-level description of the proof into a machine-checkable version, in contrast to previous work by Harrison [6, 7] who directly described the proof of the implementation of some functions in all the low-level details. The Gappa approach is more concise and more flexible in the case of a subsequent change to the code. More importantly, it is accessible to people outside the formal proof community.

This article is organized as follows. Next section describes in detail the challenges posed by automatic computation of tight bounds on ranges and errors. Section 3 describes the Gappa tool. Section 4 gives an overview on the techniques for proving an elementary function using Gappa and give an extensive example of the interactive construction of the proof.

2 Proving properties of floating-point code

2.1 Floating-point numbers are not real numbers

We have already mentioned that floating-point (FP) numbers do not possess basic properties of real numbers. The following FP code sequence, due to Dekker [8], illustrates this:

Listing 1: The Fast2Sum algorithm.

```plaintext
s = a + b;
r = b - (s - a);
```

This sequence consists only of three operations. The first one computes the FP sum of the two numbers $a$ and $b$. The second one would always return $b$ and the third one $0$, if this FP sum was exact. As the numbers here are FP numbers, however, the sum is often inexact, because of the rounding. In IEEE-754 arithmetic with round-to-nearest, under certain conditions, this algorithm computes in $r$ the error committed by this first rounding. In other words, it ensures that $r + s = a + b$ in addition to the fact that $s$ is the FP number closest to $a + b$. The Fast2Sum algorithm provides us with an exact representation of the sum of two FP numbers as a pair of FP numbers, a very useful operation.

This example illustrates an important point, which pervades all of this article: FP numbers may be an approximation of the reals that fails to ensure basic properties of the reals, but they are also a very well-defined set of rational numbers, which have other well-defined properties, upon which it is possible to build mathematical proofs such as the proof of the Fast2Sum algorithm.

Let us come back to the condition under which the Fast2Sum algorithm works. This condition is that the exponent of $a$ is larger than or equal to that of $b$, which will be true for instance if $|a| \geq |b|$. If one is to use this algorithm, one has first to prove that this condition is true. Note that alternatives to the Fast2Sum exist for the case when one is unable to prove this condition. The version by Knuth [9] requires 6 operations instead of 3. Here, being able to prove the condition, which is a property on values of the code, will result in better performance.

The proof of the properties of the Fast2Sum sequence (three FP operations) requires several pages [8], and is indeed currently out of reach of the Gappa tool, basically because it can not be reduced to manipulating ranges and errors. This is not a problem, since this algorithm has already been proven using machine checkers [4]. We consider it as a generic building-block of larger floating-point programs, and the focus of our approach is to automate the proof of such larger programs. In the case of the Fast2Sum, this means proving the condition.

Let us now introduce the class of larger FP programs that we have targeted in this work: implementations of elementary functions
2.2 Elementary functions

Current floating-point implementations of elementary functions [11, 12, 13, 14, 15] have several features that make their proof challenging:

- The code size is too large to be safely proven by hand. In the first versions of the CRlibm project, the complete paper proof of a single function required tens of pages. It is difficult to trust such proofs.
- The code is optimized for performance, making extensive use of floating-point tricks such as the Fast2Sum above. As a consequence, classical tools of real analysis cannot be straightforwardly applied. Very often, considering the same operations on real numbers would be simply meaningless.
- The code is bound to evolve for optimization purpose, because better algorithms may be found, but also because the processor technology evolves. Such changes will impose to rewrite the proof, which is both tedious and error-prone.
- Much of the knowledge required to prove error bounds on the code is implicit or hidden, be it behind the semantics of the programming language (which defines implicit parenthesing, for examples), or in the various approximations made. Therefore, the mere translation of a piece of code into a set of mathematical variables that represent the values manipulated by this code is tedious and error-prone if done by hand.

Fortunately, FP elementary function implementations also have pleasant features that make their proof tractable:

- There is a clear and simple definition of the mathematical object that the floating-point code is supposed to approximate. This will not always be the case of e.g. scientific simulation code.
- The code size is small enough to be tractable, typically less than a hundred floating-point operations.
- The control flow is simple, consisting mostly of straight-line code with a few tests but no loops.

The following elaborates on these features.

2.2.1 A primer on elementary function evaluation

The evaluation of an elementary function is classically [14, 15] performed by a polynomial approximation valid on a small interval only. A range reduction step brings the input number $x$ into this small interval, and a reconstruction step builds the final result out of the results of both previous steps. For example, the logarithm may use as a range reduction the errorless decomposition of $x$ into its mantissa $m$ and exponent $E$: $x = m \cdot 2^E$. It may then evaluate the logarithm of the mantissa, and the reconstruction consists in evaluating $\log(x) = \log(m) + E \cdot \log(2)$. Note that current implementations typically involve several layered steps of range reduction and reconstruction. With current processor technology, efficient implementations [11, 12, 16] rely on large tables of precomputed values. See the books by Muller [15] or Markstein [17] for recent surveys on the subject.

In the previous logarithm example, the range reduction was exact, but the reconstruction involved a multiplication by the irrational $\log(2)$, and was therefore necessarily approximate. This is not always the case. For example, for trigonometric functions, the range reduction involves subtracting multiples of the irrational $\pi/2$, and will be inexact, whereas the reconstruction step consists in changing the sign depending on the quadrant, which is exact in floating-point arithmetic.

It should not come as a surprise that either range reduction or reconstruction are inexact. Indeed, FP numbers are rational numbers, but for most elementary functions, it can be proven that, with the exception of a few values, the image of a rational is irrational. Therefore, in an implementation, one is bound, at some point, to manipulate numbers which are approximations of irrational numbers.

This introduces another issue which is especially relevant to elementary function implementation. One wants to obtain a double-precision FP result which is a good approximation to the mathematical result, the latter being an irrational most of the times. For this purpose, one needs to evaluate an approximation of this irrational to a precision better than that of the FP format.
2.2.2 Reaching better-than-double precision

Better-than-double precision is typically attained thanks to double-extended arithmetic on processors that support it, or double-double arithmetic, where a number is held as the unevaluated sum of two doubles, just as the 8-digit decimal number $3.8541942 \cdot 10^3$ may be represented by the unevaluated sum of two 4-digit numbers $3.854 \cdot 10^1 + 1.942 \cdot 10^{-3}$. Well-known and well-proven algorithms exist for manipulating double-double numbers [8, 9], the simplest of which is the Fast2Sum already introduced.

However these algorithms are costly, as each operation on double-double numbers requires several FP operations. In this article, we will consider implementations based on double-double arithmetic, because they are more challenging, but Gappa handles double-extended arithmetic equally well.

2.3 Floating-point errors, but not only

The evaluation of any mathematical function entails two main sources of errors.

- Approximation errors (also called methodical errors), such as the error of approximating a function with a polynomial. One may have a mathematical bound for them (given by a Taylor formula for instance), or one may have to compute such a bound using numerics [18], for example if the polynomial has been computed using Remez algorithm.

- Rounding errors, produced by most floating-point operations of the code.

The distinction between both types of errors is sometimes arbitrary: for example, the error due to rounding the polynomial coefficients to floating point numbers is usually included in the approximation error of the polynomial. The same holds for the rounding of table values, which is accounted for more accurately as approximation error than as rounding error. This point is mentioned here because a lack of accuracy in the definition of the various errors involved in a given code may lead to one of them being forgotten.

2.4 The point with efficient code

Efficient code is especially difficult to analyze and prove because of all the techniques and tricks used by expert programmers.

For instance, many floating-point operations are exact, and the experienced developer of floating-point code will try to use them. Examples include multiplication by a power of two, subtraction of numbers of similar magnitude thanks to Sterbenz’ Lemma [19], exact addition and exact multiplication algorithms (returning a double-double), multiplication of a small integer by a floating-point number whose mantissa ends with enough zeroes, etc.

The expert programmer will also do his best to avoid computing more accurately than strictly needed. He will remove from the computation some operations that are expected not to improve the accuracy of the result by much. This can be expressed as an additional approximation. However, it soon becomes difficult to know what is an approximation to what, especially as the computations are re-parenthesized to maximize floating-point accuracy.

To illustrate the resulting code obfuscation, let us introduce the piece of code that will serve as a running example along this article.

2.5 Example: A double-double polynomial evaluation

Listing 8 is an extract of the code of a sine function in the CRlibm library. These three lines compute the value of an odd polynomial $p(y) = y + s_3 \times y^3 + s_5 \times y^5 + s_7 \times y^7$ close to the Taylor approximation of the sine (its degree-1 coefficient is equal to 1). In our algorithm, the reduced argument $y$ is ideally obtained by subtracting to the FP input $x$ an integer multiple of $\pi/256$. As a consequence $y \in [-\pi/512, \pi/512] \subset [-2^{-7}, 2^{-7}]$.

However, as $y$ is irrational, the implementation of this range reduction has to return a number more accurate than a double, otherwise there is no hope of achieving an accuracy of the sine that matches floating-point double precision. In our implementation, range reduction therefore returns a double-double $y_h + y_l$. 

4
To minimise the number of operations, Horner rule is used for the polynomial evaluation: $p(y) = y + y^3 \times (s_3 + y^2 \times (s_5 + y^2 \times s_7))$. For a double-double input $y = yh + yl$, the expression to compute is thus $(yh + yl) + (yh + yl)^3 \times (s_3 + (yh + yl)^2 \times (s_5 + (yh + yl)^2 \times s_7))$.

The actual code uses an approximation to this expression: the computation will be accurate enough if all the Horner steps except the last one are computed in double-precision. Thus, $yl$ will be neglected for these iterations, and coefficients $s_3$ to $s_7$ will be stored as double-precision numbers noted $s3$, $s5$ and $s7$. The previous expression becomes:

$$(yh + yl) + yh^3 \times (s3 + yh^2 \times (s5 + yh^2 \times s7)).$$

However, if this expression is computed as parenthesized above, it will not be very accurate. Specifically, the floating-point addition $yh + yl$ will (by definition of a double-double) return $yh$, so the information held by $yl$ will be completely lost. Fortunately, the rest of the Horner evaluation also has much smaller magnitude than $yh$ (this is deduced from $y \in [-2^{-7}, 2^{-7}]$, therefore $y^3 \in [-2^{-21}, 2^{-21}]$). The following parenthesising is therefore much more accurate:

$$(yh + yl) + yh \times yh^2 \times (s3 + yh^2 \times (s5 + yh^2 \times s7))).$$

In this last version of the expression, only the leftmost addition must be accurate: we will use a Fast2Sum (which as we saw is an exact addition of two doubles returning a double-double). The other operations use the native — and therefore fast — double-precision arithmetic. We obtain the code of Listing 2.

```
Listing 2: Three lines of C
1 yh2 = yh*yh;
2 ts = yh2 * (s3 + yh2*(s5 + yh2*s7));
3 Fast2Sum(sh,sl, yh, yl + yh*ts);
```

To sum up, this code implements the evaluation of a polynomial with many layers of approximation. For instance, variable $yh2$ approximates $y^2$ through the following layers:

- $y$ was approximated by $yh + yl$ with the relative accuracy $\epsilon_{\text{argred}}$
- $yh + yl$ is approximated by $yh$ in most of the computation,
- $yh^2$ is approximated by $yh2=yh*yh$, with a floating-point rounding error.

In addition, the polynomial is an approximation to the sine function, with a relative error bound of $\epsilon_{\text{approx}}$ which is supposed known (how it was obtained it is out of the scope of this paper [13]).

Thus, the difficulty of evaluating a tight bound on an elementary function implementation is to combine all these errors without forgetting any of them, and without using overly pessimistic bounds when combining several sources of errors. The typical trade-off here will be that a tight bound requires considerable more work than a loose bound (and its proof might inspire considerably less confidence). Some readers may get an idea of this trade-off by relating the previous expression to computing a sine, for instance, with $\epsilon_{\text{approx}}$. In this case, a bound is required to ensure that the interval returned by the function contains the image of the input interval. A loose bound here means returning a larger interval than possible, and hence useless interval bloat. In both case, the tighter the bound, the better the implementation.

2.6 Previous and related work

We have not yet explained why a tight error bound is required in order to obtain a correctly rounded implementation. This question is surveyed in [3]. To sum it up, an error bound is needed to guarantee correct rounding, and the tighter the bound, the more efficient the implementation. A related problem is that of proving the behaviour of interval elementary functions [2]. In this case, a bound is required to ensure that the interval returned by the function contains the image of the input interval. A loose bound here means returning a larger interval than possible, and hence useless interval bloat. In both case, the tighter the bound, the better the implementation.

As a summary, proofs written for version of the CRlibm project up to versions 0.8 [21] are typically composed of several pages of paper proof and several pages of supporting Maple for a few lines of code. This provides an excellent
documentation and helps maintaining the code, but experience has consistently shown that such proofs are extremely error-prone. Implementing the error computation in Maple was a first step towards the automation of this process, but if it helps avoiding computation mistakes, it does not prevent methodological mistakes. Gappa was designed, among other objectives, in order to fill this void.

There has been other attempts of assisted proofs of elementary functions or similar floating-point code. The pure formal proof approach of Harrison \cite{hol,hol2} goes deeper than the Gappa approach, as it accounts for approximation errors. However it is accessible only to experts of formal proofs, and fragile in case of a change to the code. The approach of Krämer et al \cite{cva,fca} relies on operator overloading and does not provide a formal proof.

3  The Gappa tool

Gappa\footnote{\url{http://lipforge.ens-lyon.fr/www/gappa/}} extends the interval arithmetic paradigm to the field of numerical code certification \cite{bou,gar}. Given the description of a logical property involving the bounds of mathematical expressions, the tool tries to prove the validity of this property. When the property contains unbounded expressions, the tool computes bounding ranges such that the property holds. For instance, the incomplete property “$x + 1 \in [2, 3] \Rightarrow x \in [?, ?]$” can be input to Gappa. The tool answers that $[1, 2]$ is a range of the expression $x$ such that the whole property holds.

Once Gappa has reached the stage where it considers the property to be valid, it generates a formal proof that can be checked by an independent proof assistant. This proof is completely independent of Gappa and its validity does not depend on Gappa’s own validity. It can be mechanically verified by an external proof checker and included in bigger formal developments.

3.1  Floating-point considerations

Section 4 will give examples of Gappa’s syntax and show that Gappa can be applied to mathematical expressions much more complex than just $x + 1$, and in particular to floating-point approximation of elementary functions. This requires describing floating-point arithmetic expressions within Gappa.

Gappa only manipulates expressions on real numbers. In the property $x + 1 \in [2, 3]$, $x$ is just a universally-quantified real number and the operator $+$ is the usual addition on real numbers $\mathbb{R}$. Floating-point arithmetic is expressed through the use of “rounding operators”: functions from $\mathbb{R}$ to $\mathbb{R}$ that associate to a real number $x$ its rounded value $\circ(x)$ in a specific format. These operators are sufficient to express properties of code relying on most floating-point or fixed-point arithmetics.

Verifying that a computed value is close to an ideal value can now be done by computing an enclosure of the error between these two values. For example, the property “$x \in [1, 2] \Rightarrow \circ(\circ(2 \times x) - 1) - (2 \times x - 1) \in [?, ?]$” expresses the absolute error caused during the floating-point computation of the following numerical code:

\begin{verbatim}
float x = ...;
assert(1 <= x && x <= 2);
float y = 2 * x - 1;
\end{verbatim}

Infinities and NaNs (Not-a-Numbers) are not an implicit part of this formalism: The rounding operators return a real value and there is no upper bound on the magnitude of the floating-point numbers. This means that NaNs and overflows will not be generated nor propagated as they would in IEEE-754 arithmetic. However, one may use Gappa to prove very useful properties, for instance that overflows, or NaNs due to some division by 0, cannot occur in a given code: This can be expressed in terms of intervals. What one cannot prove are properties depending on the correct propagation of infinities and NaNs in the code.

3.2  Proving properties using intervals

Thanks to the inclusion property of interval arithmetic, if $x$ is an element of $[0, 3]$ and $y$ an element of $[1, 2]$, then $x + y$ is an element of the interval sum $[0, 3] + [1, 2] = [1, 5]$. This technique based on interval evaluation can be applied to any expression on real numbers. That is how Gappa computes the enclosures requested by the user.
Interval arithmetic is not restricted to this role though. Indeed the interval sum \([0, 3] + [1, 2] = [1, 5]\) do not only give bounds on \(x + y\), it can also be seen as a proof of \(x + y \in [1, 5]\). Such a computation can be formally included as an hypothesis of the theorem on the enclosure of the sum of two real numbers. This method is known as computational reflexivity [23] and allows for the proofs to be machine-checkable. That is how the formal proofs generated by Gappa can be checked independently without requiring any human interaction with a proof assistant.

Such “computable” theorems are available for the Coq [28] and HOL Light [29] proof assistants. Previous work [30] on using interval arithmetic for proving numerical theorems has shown that a similar approach can be applied for the PVS [31] proof assistant. As long as a proof checker is able to do basic computations on integers, the theorems Gappa relies on could be provided. As a consequence, the output of Gappa can be targeted to a wide range of formal certification frameworks, if needed.

3.3 Other computable predicates

Enclosures are not the only useful predicates. As intervals are connected subsets of the real numbers, they are not powerful enough to prove some properties on discrete sets like floating-point numbers or integers. So Gappa handles other classes of predicates for an expression \(x\):

\[
\text{FIX}(x, e) \equiv \exists m \in \mathbb{Z}, \ x = m \cdot 2^e \\
\text{FLT}(x, p) \equiv \exists m, e \in \mathbb{Z}, \ x = m \cdot 2^e \land |m| < 2^p
\]

As with intervals, Gappa can compute with these new predicates. For example, \(\text{FIX}(x, e_x) \land (y, e_y) \Rightarrow \text{FIX}(x + y, \min(e_x, e_y))\). These predicates are especially useful to detect real numbers exactly representable in a given format. In particular, Gappa uses them to find rounded operations that can safely be ignored because they do not contribute to the global rounding error. Let us consider the floating-point subtraction of two floating-point numbers \(x \in [3.2, 3.3]\) and \(y \in [1.4, 1.8]\). Note that Sterbenz’ Lemma is not sufficient to prove that the subtraction is actually exact, as \(\frac{3.3}{1.8} > 2\). Gappa is, however, able to automatically prove that \(o(x - y)\) is equal to \(x - y\).

As \(x\) and \(y\) are floating-point numbers, Gappa first proves that they can be represented with 24 bits each (assuming single precision arithmetic). As \(x\) is bigger than 3.2, it can then deduce it is a multiple of \(2^{-22}\), or \(\text{FIX}(x, -22)\). Similarly, it proves \(\text{FIX}(y, -23)\). The property \(\text{FIX}(x - y, -23)\) comes then naturally. By computing with intervals, Gappa also proves that \(|x - y|\) is bounded by 1.9. A consequence of these last two properties is \(\text{FLT}(x - y, 24)\): only 24 bits are needed to represent \(x - y\). So \(x - y\) is representable by a single-precision floating-point number.

There are also some specialized predicates for enclosures. The following one expresses the range of an expression \(u\) with respect to another expression \(v\):

\[
\text{REL}(u, v, [a, b]) \equiv -1 < a \land \exists e \in [a, b], \ u = v \cdot (1 + e)
\]

This predicate is seemingly equivalent to the enclosure of the relative error \(\frac{u - v}{v}\). It allows, however, to simplify proofs, as the error can now be manipulated even when \(v\) is potentially zero. For example, the relative rounding error of a floating-point addition vanishes on subnormal numbers (including zero) and is bounded elsewhere, so the following property holds: \(\text{REL}(o(x + y), x + y, \{-2^{-53}, 2^{-52}\})\) when rounding to nearest in double precision.

3.4 Gappa’s engine

Because basic interval evaluations do not keep track of correlations between expressions sharing the same terms, some computed ranges may be too wide to be useful. This is especially true when bounding errors. For example, when bounding the absolute error \(o(a) - b\) between an approximation \(o(a)\) and an exact value \(b\), the simplest option is to first compute the ranges of \(o(a)\) and \(b\) separately and then subtract them. However, first rewriting the expression as \((o(a) - a) + (a - b)\) and then bounding \(o(a) - a\) (a simple rounding error) and \(a - b\) separately before adding their ranges usually gives a much tighter result. These rules are inspired by techniques developers usually apply by hand in order to certify their numerical applications.

Gappa includes a database of such rewriting rules (section 3.5 shows how the user may expand this database). The tool applies them automatically, so that it can bound expressions along various evaluation paths. Since any of these
resulting intervals encloses the initial expression, their intersection does, too. Gappa keeps track of the paths that lead to the tightest interval intersection and discards the others, so as to reduce the size of the final proof. It may happen that the resulting intersection is empty; it means that there is a contradiction between the hypotheses of the logical property and Gappa will use it to prove all the goals of the logical property.

Once the logical property has been proved, a formal proof is generated by retracing the paths that were followed when computing the ranges.

3.5 **Hints**

When Gappa is not able to satisfy the goal of the logical property, this does not necessarily mean that the property is false. It may just mean that Gappa has not enough information about the expressions it tries to bound.

It is possible to help Gappa in these situations by providing *rewriting hints*. These are rewriting rules similar to those presented above in the case of rounding, but whose usefulness is specific to the problem at hand.

3.5.1 **Explicit hints**

A hint has the following form:

\[ \text{Expr1} \rightarrow \text{Expr2}; \]

It is used to give the following information to Gappa: “I believe for some reason that, should you need to compute an interval for \( \text{Expr1} \), you might get a tighter interval by trying the mathematically equivalent \( \text{Expr2} \)”. This fuzzy formulation is better explained by considering the following examples.

1. The “some reason” in question will typically be that the programmer knows that expressions \( A \), \( B \) and \( C \) are different approximations of the same quantity, and furthermore that \( A \) is an approximation to \( B \) which is an approximation to \( C \). As previously, this means that these variables are correlated, and the adequate hint to give in this case is

\[ A - C \rightarrow (A - B) + (B - C); \]

It will suggest to Gappa to first compute intervals for \( A-B \) and \( B-C \), and then to sum them to get an interval for \( A-C \).

As there are an infinite number of arbitrary \( B \) expressions that can be inserted in the right hand side expression, Gappa does not try to apply every possible rewriting rule when it encounters \( A-C \). However, as 3.5.2 will show, Gappa usually infers some useful \( B \) expressions and applies the rewriting rules automatically.

2. Relative errors can be manipulated similarly. The hint to use in this case is

\[ \frac{A-C}{C} \rightarrow \frac{A-B}{B} + \frac{B-C}{C} + \left( \frac{A-B}{B} \right) \cdot \left( \frac{B-C}{C} \right); \]

This is still a mathematical identity, as one may check easily. Again, Gappa tries to infer some useful \( B \) expressions and to apply the corresponding rewriting rules.

3. When \( x \) is an approximation of \( MX \) and a relative error \( \epsilon = \frac{x - MX}{MX} \) is known by the tool, \( x \) can be rewritten \( MX \cdot (1 + \epsilon) \). This kind of hint is useful in combination with the following one.

4. When manipulating fractional terms such as \( \frac{\text{Expr1}}{\text{Expr2}} \) where \( \text{Expr1} \) and \( \text{Expr2} \) are correlated (for example one approximating the other), the interval division fails to give useful results if the interval for \( \text{Expr2} \) comes close to 0. In this case, one will try to write \( \text{Expr1} = A \cdot \text{Expr3} \) and \( \text{Expr2} = A \cdot \text{Expr4} \), so that the interval on \( \text{Expr4} \) does not come close to 0 anymore. The following hint is then appropriate:

\[ \text{Expr1} / \text{Expr2} \rightarrow \text{Expr3} / \text{Expr4}; \]

This rewriting rule is only valid if \( A \) is not zero, so the case \( A = 0 \) has to be handled separately. So that Gappa does not apply the rule in an invalid context, a constraint on \( A \) can be added. The rule thus becomes:
All these hints are correct if both sides are mathematically equivalent. Gappa therefore checks this automatically. If the test fails, it emits a warning to the user that he or she must review the hint by hand. Therefore, writing even complex hints is very safe: one may not introduce an error in the proof by writing hints which do not emit warnings.

Besides, useless hints may consume execution time as Gappa tries in vain to use them, but if they are useless, they will be silently ignored in the final proof. Therefore, writing useless hints is essentially harmless.

### 3.5.2 Automatic hints

After using Gappa to prove several elementary functions, one thing became clear: Users kept writing the same hints, typically of the three first kinds enumerated in 3.5.

Gappa was therefore modified to introduce a new kind of hint:

\[ \text{Expr1} \sim \text{Expr2}; \]

that reads “Expr1 approximates Expr2”. This has the effect of introducing rewriting hints both for absolute and relative differences involving Expr1 or Expr2. There may be useless hints among such automatic hints, but again they will be mostly harmless.

For instance, when it encounters an expression of the form \( \text{Expr1} - \text{Expr3} \) (for any expression \( \text{Expr3} \)), Gappa automatically tries the rule \( \text{Expr1} - \text{Expr3} \rightarrow (\text{Expr1} - \text{Expr2}) + (\text{Expr2} - \text{Expr3}) \). And when it encounters \( \text{Expr3} - \text{Expr2} \), it tries the rewriting rule \( \text{Expr3} - \text{Expr2} \rightarrow (\text{Expr3} - \text{Expr1}) + (\text{Expr1} - \text{Expr2}) \).

By default, Gappa assumes that \( \text{Expr1} \) approximates \( \text{Expr2} \) if \( \text{Expr1} \) is the rounded value of \( \text{Expr2} \). It also makes this assumption when an enclosure of the absolute or relative error between \( \text{Expr1} \) and \( \text{Expr2} \) appears in the hypotheses of the logical proposition Gappa has to prove.

Remark: It is very important, in the various differences appearing in all these expressions, that the least accurate term is written first and the most accurate written last. The main reason is that the theorems of Gappa’s database apply to expressions written in this order. This ordering convention prevents a combinatorial explosion on the number of paths to explore.

### 3.5.3 Bisection and dichotomy hints

Finally, it is possible to instruct Gappa to split some intervals and perform its exploration on the resulting sub-intervals. There are several possibilities. For instance, the following hint

\[ \text{z in } (-1,2); \]

reads “Better enclosures may be obtained by separately considering the sub-cases \( z \leq -1, -1 \leq z \leq 2, \) and \( 2 \leq z \).”

The following hint finds the splitting points automatically by performing a dichotomy on the interval of \( z \) until the part of the goal corresponding to \( \text{Expr} \) as been satisfied for all the sub-intervals of \( z \).

\[ \text{Expr } \text{z}; \]

### 3.5.4 Writing hints in an interactive way

Gappa has evolved to include more and more automatic hints, but most real-world proofs still require writing complex, problem-specific hints. Finding the right hint that Gappa needs could be quite complex and would require completely mastering its theorem database and the algorithms used by its engine. Fortunately, a much simpler way is to build the proof incrementally and question the tool by adding and removing intermediate goals to prove, as the extended example in next section will show. Before that, we first describe the outline of the methodology we use to prove elementary functions.
4 Proving elementary functions using Gappa

As in every proof work, style is important when working with Gappa: in a machine-checked proof, bad style will not in principle endanger the validity of the proof, but it may prevent its author to get to the end. In the CRlibm framework, it may hinder acceptance of machine-checked proofs among new developers.

Gappa does not impose a style, and when we started using it there was no previous experience to get inspiration from. After a few months of use, we had improved our “coding style” in Gappa, so that the proofs were much more concise and readable than the earlier ones. We had also set up a methodology that works well for elementary functions. This section is an attempt to describe this methodology and style. We are aware that they may be inadequate for other applications, and that even for elementary functions they could be improved further.

The methodology consists in three steps, which correspond to the three sections of a Gappa input file.

• First, the C code is translated into Gappa equations, in a way that ensures that the Gappa proof will indeed prove some property of this program (and not of some other similar program). Then equations are added describing what the program is supposed to implement. Usually, these equations are also in correspondence with the code.

• Then, the property to prove is added. It is usually in the form hypotheses -> properties, where the hypotheses are known bounds on the inputs, or contribution to the error determined outside Gappa, like the approximation errors.

• Finally, one has to add hints to help Gappa complete the proof. This last part is built incrementally.

The following sections detail these three steps.

4.1 Translating a FP program

We consider again the following C code, where we have added the constants:

1. s3 = -1.6666666666666665741e-01;
2. s5 = 8.3333333333333332177e-03;
3. s7 = -1.9841269841269841253e-04;
4. yh2 = yh*yh;
5. ts = yh2 * (s3 + yh2*(s5 + yh2*s7));
6. Fast2Sum(sh,sl, yh, yl + yh*ts);

There is a lot of rounding operations in this code, so the first thing to do is to define Gappa rounding operators for the rounding modes used in the program. In our example, we use the following line to define IEEEdouble as a shortcut for IEEE-compliant rounding to the nearest double, which is the mode used in CRlibm.

@IEEEdouble = float<ieee_64,ne>;

Then, if the C code is itself sufficiently simple and clean, the translation step only consists in making explicit the rounding operations implicit in the C source code. To start with, the constants s3, s5 and s7 are given as decimal strings, and the C compilers we use convert them to (binary) double-precision FP numbers with round to nearest. We ensure that Gappa works with these same constants as the compiled C code by inserting explicit rounding operations:

s3 = IEEEdouble(-1.6666666666666665741e-01);
... 

Then we have to do the same for all the roundings hidden behind C arithmetic operations. Adding by hand all the rounding operators, however, would be tedious and error-prone, and would make the Gappa syntax so different from the C syntax that it would degrade confidence and maintainability. Besides, one would have to apply without error the rules (well specified by the C99 standard) governing for instance implicit parentheses in a C expression. For these reasons, Gappa has a syntax that instructs it to perform this task automatically. The following Gappa lines...

yh2 IEEEdouble= yh * yh;
ts IEEEdouble= yh2 * (s3 + yh2*(s5 + yh2*s7));
define the same mathematical relation between their right-hand side and left-hand side as the corresponding lines of
the C programs. This, of course, is only true under the following conditions:

- all the C variables are double-precision variables,
- the Gappa variables on the right-hand side represent them,
- the compiler/OS/processor combination used to process the C code respects the C99 and IEEE-754 standards
  and computes in double-precision arithmetic.

Finally, we have to express in Gappa the Fast2Sum algorithm. Where in C it is a macro or function call, for our
purpose we prefer to ignore this complexity and simply express in Gappa the resulting behaviour, which is a sum
without error (we have here to trust an external proof of this behaviour [8, 9]):

\[
\begin{align*}
  r & \quad \text{IEEE} = y_l + y_h \times ts; \\
  s & \quad = y_h + r; \quad \# \text{ the Fast2Sum is exact. } s \text{ is } s_h + s_l
\end{align*}
\]

Note that we are interested in the relative error of the sum s with respect to the exact sine, and for this purpose the
fact that s has to be represented as a sum of two doubles in C is irrelevant.

More importantly, this adds another condition for this code translation to be faithful: As the proof of the Fast2Sum
has as hypothesis that the exponent of y_h is larger than or equal to that of r, we now have to prove that. We will
simply add this goal to the theorem to prove.

As a summary, for straight-line program segments with mostly double-precision variables, a set of corresponding
Gappa definitions can be obtained straightforwardly by just replacing the C \( \text{= with Gappa IEEE} \text{=} \), a very safe
operation.

4.2 Defining ideal values

To analyse this code, we now need a “mathematically ideal” definition of all the variables, a reference with respect
to which the error is computed. This notion of mathematically ideal may be quite subtle: What is the mathematically
ideal of \( y_h^2 \)? It could be

- the exact square of \( y_h \) (without rounding), or
- the exact square of \( y_h + y_l \) that \( y_h \) approximates, or
- the exact square of the ideal reduced argument \( y \), which is usually irrational.

The right choice depends on the properties to prove. Here, the mathematically ideal value for both \( y_h + y_l \) and \( y_h \)
will be the ideal reduced argument, which we note \( M_y \). Similarly, the purest mathematical value that \( y_h^2 \) approximates
is noted \( M_y^2 \) and will be defined as \( M_y^2 = M_y \times M_y \).

For the polynomial approximation \( ts \), we could choose, as mathematical ideal, either the value of the function
that the polynomial approximates, or the value of the same polynomial, but computed on \( M_y \) and without rounding
error. Here we chose the latter, although it is the lesser ideal.

Here come a few naming conventions. The first was obviously that the Gappa variables that mimic C variables
have the same name. We also impose the convention that such variables begin with a lowercase letter. In addition,
Gappa variables for mathematically ideal terms will begin with a “\( M \)”. The other intermediate Gappa variables should
begin with capital letters to distinguish them from variables mimicking the code. Of course, related variables should
have related and, wherever possible, explicit names. Again, these are conventions and are part of a proof style, not part
of Gappa syntax: the capitalization will give no information to the tool, and neither will the fact that variables have
related names.

For instance, it will be convenient to define a variable equal to \( y_h + y_l \):

\[
Yhl = y_h + y_l;
\]
### 4.3 Defining what the code is supposed to compute

Defining mathematically ideal values resumes to defining in Gappa what the C code is supposed to implement. For instance, using our previous conventions, the line for $t_s$ was probably evaluating the value of the same polynomial of the ideal $M_y$:

```c
My2 = My*My;
Mts = My2 * (s3 + My2*(s5 + My2*s7));
```

We have kept the polynomial coefficients in lower case: As already discussed in Section 2, the polynomial thus defined nevertheless belongs to the set of polynomial with real coefficients, and we have means to compute (outside Gappa) a bound of its relative error with respect to the function it approximates.

The link between $t_s$ and the polynomial approximating the sine is also best expressed using mathematically ideal values:

```c
PolySinY = My + My*Mts;
```

To sum up, $PolySinY$ is the actual polynomial with the same coefficients $s_3$ to $s_7$ as in the C code, but evaluated without rounding error, and evaluated on the ideal value that $y_h+y_l$ approximates.

Another approach could be to use a Taylor polynomial, in which case the approximation error would be given by the rest in the Taylor formula, the ideal polynomial would be the Taylor one, it would have ideal Taylor coefficients (beginning with $M$), some of which would have to be rounded to FP numbers to appear in the program (lowercase).

Gappa could handle it, too, but it would be less convenient.

Another crucial question is, how do we define the real, ideal, mathematical function which we eventually approximate? Gappa has no built-in sine or logarithm. The current approach can be described in English as: “$\sin(M_y)$ is a value which, as long as $M_y$ is smaller than $6.29e-3$, remains within a relative distance of $2.26e-24$ of our ideal polynomial”. In Gappa, this will translate to some hypotheses in the property to prove:

```latex
|Y_hl| in [0, 6.29e-03] /
\(\frac{(PolySinY - SinY)/SinY}{\leq 2.26e-24}
/
\(\ldots\) # (more hypotheses, see below)
\)
\(\rightarrow \) epstotal in ?
```

Here the interval of $Y_hl$ is defined by the range reduction, and its bound has been computed separately: it is $\pi/512$, plus some margin that accounts for the inexactness of argument reduction.

Similarly, the relative distance between the sine and the polynomial on this interval is computed outside Gappa. We used to use Maple’s infinite norm, but it only returns an approximation, so this was in principle a weakness of the proof. We now use a safer, interval-based approach [18], implemented in the Sollya tool².

Of course this tool provides a theorem which could be expressed as

```latex
|Y_hl| in [0, 6.29e-03] \rightarrow |(PolySinY - SinY)/SinY| \leq 2.26e-24. We just inject the property of this theorem as an hypothesis in Gappa.
```

Concerning style, it will be more convenient to have a variable defined as this approximation error. Similarly, it will make the proof much clearer and concise to add, from the beginning, as many definitions as possible for the various terms and errors involved in the computation:

```c
Epsargred = (Yhl - My)/My;  # argument reduction error
Epsapprox = (PolySinY - SinY)/SinY;  # polynomial approximation error
Epsround = (s - PolySinY)/PolySinY;  # rounding errors in the polynomial evaluation
Epstotal = (s - SinY)/SinY;  # total error
```

### 4.4 Defining the property to prove

With the previous introduction, the theorem to prove, expressed as implications using classical first-order logic, is stated as follows:

```latex
http://sollya.gforge.inria.fr/
```
# Hypotheses
| Yhl | in [0, 6.29e-03]  
\/ | Epsargred <= 2.53e-23  
\/ | Epsapprox <= 2.26e-24  
->
| Epstotal in ?  
\/ | r/yh | in [0,1]  

The full initial Gappa script is given below. It adds a more accurate definition of $yh$ and $yl$, stating that they are double-precision numbers and that they form a disjoint double-double. It also adds a lower bound on the absolute value of the reduced argument, obtained thanks to Kahan/Douglas algorithm. This lower bound is important because it will enable most values to stay away from zero, which ensures that relative errors are not arbitrarily big due to underflow.

Listing 3: The initial Gappa file.

```
@IEEEdouble = float<ieee_64,ne>;

# yh+yl is a double-double (call it Yhl)
yh = IEEEdouble(dummy1);
yl = IEEEdouble(dummy2);
Yhl = yh + yl;  # Below, there is also an hypothesis stating that yl<ulp(yh)

#--------------- Transcription of the C code -----------------------------
s3 = IEEEdouble(-1.6666666666666665741e-01);
s5 = IEEEdouble( 8.3333333333333332177e-03);
s7 = IEEEdouble(-1.9841269841269841253e-04);
yh2 IEEEdouble= yh * yh;
ts s3 + yh2*(s5 + yh2*s7));
 r IEEEdouble= yl + yh*ts;
s = yh + r;  # no rounding, it is the Fast2Sum

#-------- Mathematical definition of what we are approximating --------
My2 = My*My;
Mts = My2 * (s3 + My2*(s5 + My2*s7));
PolySinY = My + My*Mts;

Epsargred = (Yhl - My)/My;  # argument reduction error
Epsapprox = (PolySinY - SinY)/SinY;  # polynomial approximation error
Epsround = (s - PolySinY)/PolySinY;  # rounding errors in the polynomial evaluation
Epstotal = (s - SinY)/SinY;  # total error

#---------------------- The theorem to prove ----------------------------
{
  # Hypotheses
  | yl / yh | <= 1b-53  
\/ | Yhl | in [1b-200, 6.29e-03]  # lower bound guaranteed by Kahan-Douglas algorithm  
\/ | Epsargred <= 2.53e-23  
\/ | Epsapprox <= 2.26e-24  
->
| Epstotal in ?  
\/ | r/yh | <= 1
```

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4.5 With a little help from the user

Invoking Gappa on this file produces the following output:

Warning: no path was found for Epstotal.
Warning: no path was found for |r / yh|.

Results for |yl / yh| in [0, 1.11022e-16] and |Yhl| in [6.22302e-61, 0.00629] and |Epsargred| in [0, 2.53e-23] and |Epsapprox| in [0, 2.26e-24]:
Warning: some enclosures were not satisfied.

This means that Gappa needs some help, in the form of hints. Where to start? There are several way to interact with the tool to understand where it fails.

- We may add additional goals to obtain enclosures for intermediate variables. For instance, adding the goal |

|My| in ?, we obtain the following answer

|My| in [0, 0.00629]

Gappa was able to deduce this enclosure from the enclosure of Yhl (hypothesis) and the definition of Epsargred. Similarly, we may check for instance that the built-in engine is able to build a good enclosure of PolySinY, but not of S.

- We may add additional hypotheses and see what progress they entail. For instance, providing a dummy Epsround as an hypothesis allows Gappa to complete the proof, thanks to its automatic hints.

This way it is possible to track the point where Gappa’s engine gets lost, and provide hints to help it.

In our case, the best thing to do is to express all the approximation layers detailed in Section 2.5. Written as Gappa equations, we get:

```
# Layers of approximation on s
S1 = yh + (yl + IEEEdouble(yh*ts));  # s without last rounding
S2 = yh + (yl + yh*ts);            # removing penultimate rounding, too
S3 = (yh+yl) + (yh+yl)*ts;         # putting back yl which was neglected
Eps1 = (s-S1)/S1;
Eps2 = (S1-S2)/S2;
Eps3 = (S2-S3)/S3;
Eps4 = (S3-PolySinY)/PolySinY;
```

Remark again that all these relative errors are defined relatively to the most accurate term.

We may add goals for these new relative errors: Gappa will be unable to bound any of them. We have to provide hints.

Consider only Eps4, the relative difference between S3 and PolySinY— which we saw Gappa is able to bound. Both S3 and PolySinY are polynomial expressions without any rounding, and with identical coefficients. Therefore, the difference between them resumes to the difference between Yhl=yh+yl, used in S3, and My, used in PolySinY. We precisely have a measure of this difference: it is Epsargred. The hint we have to provide to Gappa should therefore express Eps4 as a function of Epsargred which, when evaluated by intervals, will provide a tight enclosure. Here is a generic technique to obtain such an hint. We start with Eps4 -> (S3-PolySinY)/PolySinY, which is just the definition of Eps4, and we rewrite it incrementally until we have obtained an expression involving Epsargred. In the following hint, we have left, for the purpose of this tutorial, the intermediate rewriting steps commented out.

```
Eps4 ->
# (S3-PolySinY)/PolySinY;
# S3/PolySinY - 1;
# ((yh+yl) + (yh+yl)*ts) / (My + My*Mts) - 1;
# ((yh+yl)/My) * (1+ts)/(1+Mts) - 1;
```
Considering the orders of magnitudes (see Section 2.5), a naive interval evaluation of this last expression will be very accurate. Indeed, $Mts$ as well as $ts$ are very small compared to 1, therefore the first term is close to $Epsargred$. The second is the relative error of $ts$ with respect to $Mts$ (expected to be no larger than $2^{-52}$), multiplied by $Mts$ which is smaller than $2^{-14}$. We therefore have a sum of two small terms which should provide a small enclosure.

Still, even with this hint, Gappa still fails to provide an enclosure for $Eps4$. Adding the goals $Mts$ in ? and $ts$ in ?, we observe that $Mts$ is properly enclosed, but not $ts$. We therefore add a definition of the relative error of $ts$ with respect to $Mts$:

$$\text{EpstsMts} = \frac{(ts-Mts)}{Mts};$$

and we perform the same analysis: we describe the succession of approximation layers between $ts$ and $Mts$, define intermediate error terms for them, and provide hints for bounding them. This will in turn require to explain to Gappa how to go from $by$ to $yh2$ through three approximation layers.

We will not detail this process line by line. The final Gappa script is given in appendix, and is available from the distribution of CRlibm\(^3\).

### 4.6 Summing up

Writing hints is the most time-consuming part of the proof, because it is the part where the designer’s intelligence is required. However, we hope to have shown that it may be done very incrementally.

The example chosen in this article is actually quite complex: its Gappa proof consists of more than 150 lines, half of which are hints. The bound found on $Eps_{total}$ is $2^{-67.24}$ and is obtained in a few seconds on a recent machine (the time can be longer when there is a dichotomy). The resulting Coq proof is more than 7000 lines long.

Some functions are simpler. We could write the proof of a logarithm implementation \([5]\) with a few hints only \([33]\). One reason is that the logarithm never comes close to 0, so the full proof can be handled only with absolute errors, for which writing hints is much lighter.

### 5 Conclusion and perspectives

Validating tight error bounds on the low-level, optimized floating-point code typical of elementary functions has always been a challenge, as many sources of errors cumulate their effect. Gappa is a high-level proof assistant that is well suited to this kind of proofs.

Using Gappa, it is easy to translate a part of a C program into a mathematical description of the operations involved with fair confidence that this translation is faithful. Expressing implicit mathematical knowledge one may have about the code and its context is also easy. Gappa uses interval arithmetic to manage the ranges and errors involved in numerical code. It handles most of the decorrelation problems automatically thanks to its built-in rewriting rules, and an engine which explores the possible rewriting of expressions to minimize the size of the intervals. If decorrelation remains, Gappa allows one to provide new rewriting rules, but checks them. All this is well founded on a library of theorems which allow the obtained computation to be translated to a proof checkable by a lower-level proof assistant such as Coq and PVS. Finally, the tool can be questioned during the process of building the proof so that this process may be conducted interactively.

Therefore, it is possible to get quickly a fully validated proof with good confidence that this proof indeed proves property of the initial code. Gappa is by no means automatic: to apply it on a given piece of code requires exactly the same knowledge and cleverness a paper proof would. However, it requires much less work.

The current CRlibm distribution contains several bits of proofs using Gappa at several stages of its development. Although this development is not over, the current version (0.9) is very stable and we may safely consider generalizing

\(^3\)http://lipforge.ens-lyon.fr/www/crlibm/
the use of this tool in the future developments of CRlibm. It also took 6 months to develop a methodology and style well suited to the validation of elementary functions. This paper presented this aspect as well. Very probably, new problems will arise as we try to apply this methodology to new functions, so that it will need to be refined further.

Iterative codes are currently out of scope of our methodology, although it could be used for instance to prove loop invariants.

A Complete Gappa script

Listing 4: The complete Gappa file.

```gappa
# test with gappa -Munconstrained < sin.gappa
# The proof is not complete, as it doesn’t work without -Munconstrained.
# It’s OK for practical purposes, but it takes some more work to get a formal proof.
@IEEEdouble = float<ieee_64,ne>;
# Convention 1: uncapitalized variables match the variables in the C code. Other variables begin with a capital letter
# Convention 2: variables beginning with "M" are mathematical ideal
# yh+yl is a double-double (call it Yhl)
yh = IEEEdouble(dummy1);
yl = IEEEdouble(dummy2);
Yhl = yh + yl; # There is also an hypothesis stating that yl<ulp(yh)
#--------------- Transcription of the C code ---------------
s3 = IEEEdouble(-1.6666666666666665741e-01);
s5 = IEEEdouble(8.3333333333333332177e-03);
s7 = IEEEdouble(-1.9841269841269841253e-04);
yh2 IEEEdouble= yh * yh;
ts =IEEEdouble= yh2 * (s3 + yh2*(s5 + yh2*s7));
r IEEEdouble= yl + yh*ts;
s = yh + r; # no rounding, it is the Fast2Sum
#-------- Mathematical definition of what we are approximating --------
My2 = My*My;
Mts = My2 * (s3 + My2*(s5 + My2*s7));
PolySinY = My + My*Mts;
Epsargred = (Yhl - My)/My; # argument reduction error
Epsapprox = (PolySinY - SinY)/SinY; # polynomial approximation error
Epsround = (s - PolySinY)/PolySinY; # rounding errors in the polynomial evaluation
Epstotal = (s - SinY)/SinY; # total error
# Layers of approximation on s
S1 = yh + (yl + IEEEdouble(yh*ts)); # remove last round
S2 = yh + (yl + yh*ts);
S3 = (yh+yl) + (yh+yl)*ts; # put yl back in
S4 = (s-S1)/S1;
S5 = (S1-S2)/S2;
S6 = (S2-S3)/S3;
S7 = (S3-PolySinY)/PolySinY;
```

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yhts = IEEEdouble(yh*ts);  # just to make the hints lighter
p3 IEEEdouble=s3 + yh2*(s5 + yh2*s7);  # idem

tsNoRound = yh2 * (s3 + yh2*(s5 + yh2*s7));

# A few definitions mostly to benefit from automatic hints.
EpstsMts = (ts-Mts)/Mts;
EpstsNoRoundMts = (tsNoRound - Mts)/Mts;
Epsy2 = (yh2-My2)/My2;
Epsy2_argred = (Yhl*Yhl-My2)/My2;
Epsy2_negl_yl = (yh*yh-Yhl*Yhl)/(Yhl*Yhl);
Epsy2_rnd = (yh2-yh2*yh)/(yh*yh);

#---------------------------------- The theorem to prove -------------------
{
# Hypotheses
|yl / yh| <= 1b-53
|Yhl| in [1b-200, 6.29e-03]  # lower bound guaranteed by Kahan-Douglas algorithm
|yh| in [1b-1000, 1]  # some huge range for ensuring that yh is not zero
|Epsargred| <= 2.53e-23
|Epsapprox| <= 2.26e-24

->

#goal to prove
Epstotal in ?# [-1b-67, 1b-67]
|r/yh| <= 1
|My| in [1b-400, 6.29e-03]
}

# ---------------------- Hints ------------------------
$ Yhl in (0);

# First, the hints for Epsround
s~S1;
S1~S2;
S2~S3;
S3~PolySinY;

Eps4 -> # (S3-PolySinY)/PolySinY;
# S3/PolySinY = 1;
# ((yh+yhl)/(yh+yhl)*ts) / (My + My*Mts) - 1;
# ((yh+yhl)/My) * (1+ts)/(1+Mts) - 1;
# (Epsargred+1) * (1+ts)/(1+Mts) - 1;
# Epsargred * (1+ts)/(1+Mts) + 1 * (1+ts)/(1+Mts) - 1;
# Epsargred * (1+ts)/(1+Mts) + (ts-Mts)/(1+Mts);
# Epsargred * (1+ts)/(1+Mts) + Mts*((ts-Mts)/Mts) / (1+Mts);

# Now we just need to bound ts-Mts:
(s3 - tsNoRound - Mts)/Mts ->

# yh2/My2  * (s3 + yh2*(s5 + yh2*s7)) / (s3 + My2*(s5 + My2*s7)) - 1 ;
(1+Epsy2)  * (s3 + yh2*(s5 + yh2*s7)) / (s3 + My2*(s5 + My2*s7)) -1;

# Now we just need to express My2 in terms of yh2 and Epsy2
My2 -> yh2/(1+Epsy2);
\[ (y_h - Y_{hl}) / Y_{hl} \rightarrow 1 / (1 + y_l / y_h) - 1; \]

Eps3 ->
\[
# (S_2 - S_3) / S_3
\]
\[
# S_2 / S_3 - 1;
\]
\[
# (y_h + (y_l + y_h*ts)) / ((y_h+y_l) + (y_h+y_l)*ts) - 1 ;
\]
\[
# ((y_h+y_l) + (y_h+y_l)*ts - y_l*ts) / ((y_h+y_l) + (y_h+y_l)*ts) - 1 ;
\]
\[
# - y_l*ts / ((y_h+y_l) + (y_h+y_l)*ts) ;
\]
\[
# - (y_l/Y_{hl}) * (ts / (1+ts)) ;
\]
\[
# change sign to have the expression of a rounding error
\]

Eps2 ->
\[
# (S_1 - S_2) / S_2;
\]
\[
# (y_h + (y_l + IEEEdouble(y_h*ts))) / (y_h + (y_l + y_h*ts)) -1 ;
\]
\[
# (IEEEdouble(y_h*ts) - y_h*ts) / (y_h + y_l + y_h*ts) ;
\]
\[
# (IEEEdouble(y_h*ts) - y_h*ts)/(y_h*ts)) / (y_h+y_l)/(y_h*ts) + 1 } ;
\]
\[
# ((IEEEdouble(y_h*ts) - y_h*ts)/(y_h*ts)) / (1 + y_l/y_h + ts ) ;
\]
\[
y_h t s / y_h \rightarrow ts*((y_h t s-y_h*ts)/(y_h*ts) + 1); 
\]
\[
(y_l+y_h t s)/y_h \rightarrow y_l/y_h + y_h t s/y_h;
\]

References


